

## **Amendments to the Specification**

Please amend paragraph [0057] as follows:

[0057] Referring to Fig. 7 a satellite based telepresence system is shown. Here delays in the order of seconds between head motion and image display result. Further, the delays are not always predictable. Here an HMD 101 is shown positioned on the head of an operator 105. The HMD is provided with a head tracker 103 for sensing position data relative to the HMD. The HMD is also coupled with a computer 107 for providing display data to the HMD and for providing the HMD position data to a communications link 108. The communications link 108 uplinks the HMD position data to a satellite 117 from which it is transmitted to a transceiver 116. A computer 115 in communication with the transceiver provides the data to a gimbal 113 for repositioning a camera 111 in accordance therewith. The camera 111 captures images which are provided along a reverse communication path - computer 115, transceiver 116, satellite 117, communications link 108 - to the computer 107. Optionally, a different return path is used. There the image data is processed for display within the HMD 101. With the images, camera position data sensed by a sensor 114 is also provided. The camera position data is associated with an image or images captured at approximately a time the camera 111 was in that sensed position.